



Molecular and Cellular Computing

Lecture series at Universidad Politécnica de Madrid

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Day 2: From *in vitro* to *in vivo*

1. Models, Lab Work and the Transition

Introduction

- After Adleman's original experiment (and Lipton's follow-up paper) there quickly followed a large number of theoretical papers
- We have already covered the parallel filtering model
- In this lecture we summarise some of the more significant theoretical models of DNA computation

Boolean circuits

- Followed on from Ogiwara and Ray
- We want to simulate circuits of NAND gates
- Useful function - provides complete basis
- Advances in silicon (eg. cMOS) often start with NAND - interesting historical precedent
- Outputs 0 iff both inputs=1, 1 otherwise
- Negated AND function

M. Ogiwara and A. Ray, Simulating Boolean circuits on a DNA computer. First Annual Conference on Computational Molecular Biology, pages 326 - 331, ACM Press, 1997. The final version: *Algorithmica* **25**:239 - 250, 1999.

Representing Gates in DNA

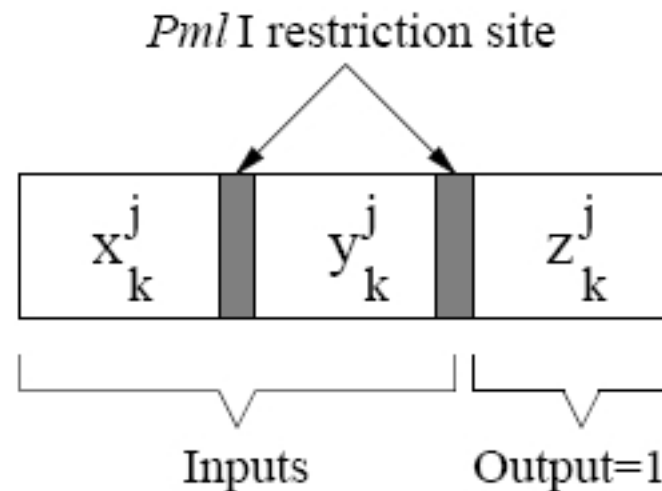
- We represent each gate by a single strand
- 3 components - 2 inputs, and output=1
- Output section present=gate outputs 1
- If a gate takes its inputs from gates x and y , its *first* input section is the complement of x 's output section, and its *second* input section is the complement of y 's output section

Restriction enzymes

- Destroy double-stranded DNA
- Recognise a specific *restriction site* (eg. GATC)
- RS embedded between two input sections
- Only made d.s. If both input sections are covered
- Gates only *destroyed* if both inputs=1



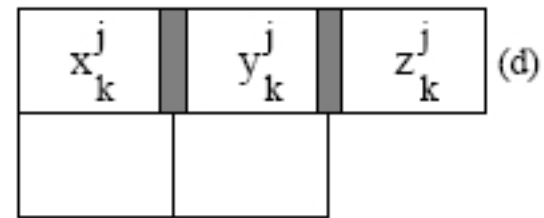
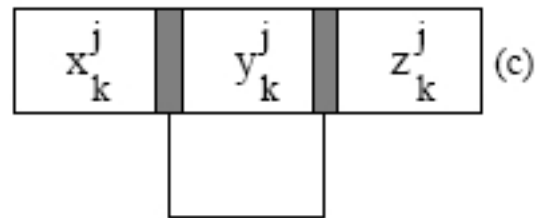
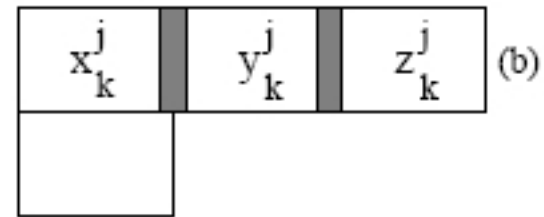
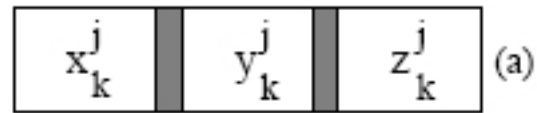
- Consider gate j at circuit level k
- The two input sequences are represented by x_k^j and y_k^j
- The output sequence is represented by z_k^j





Circuit Construction

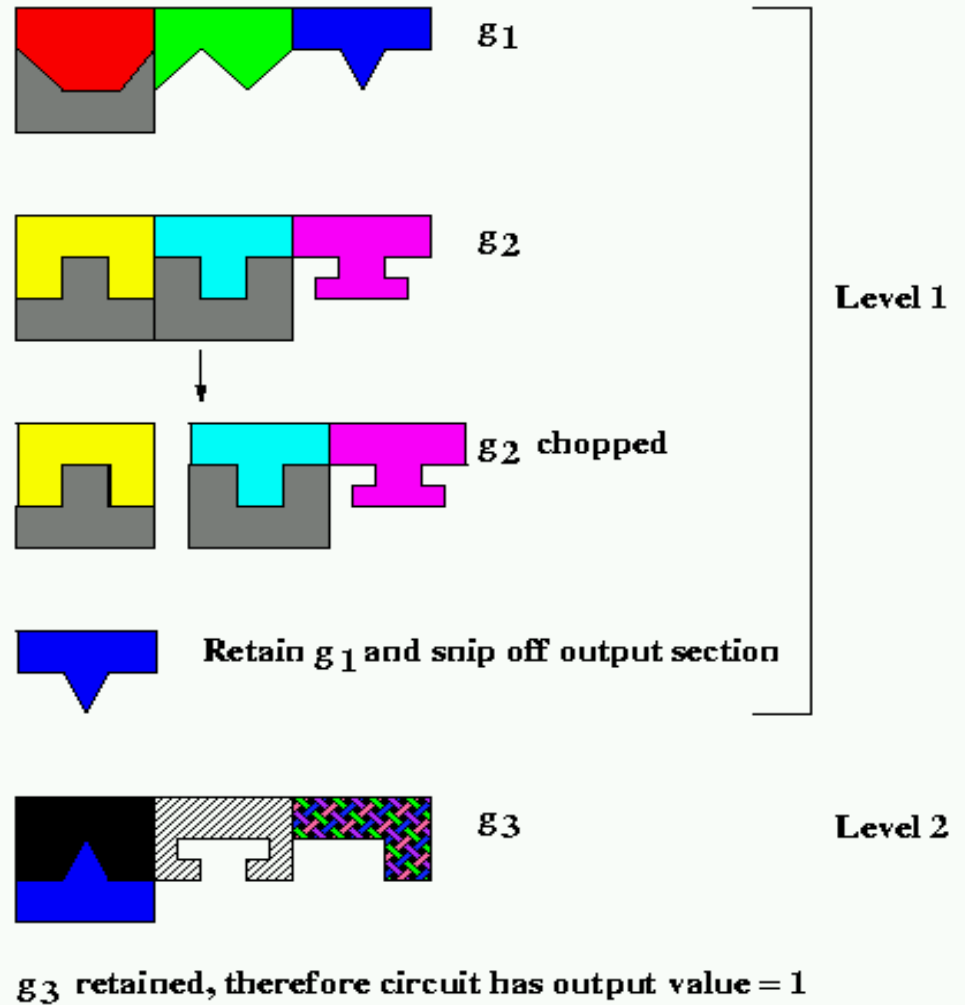
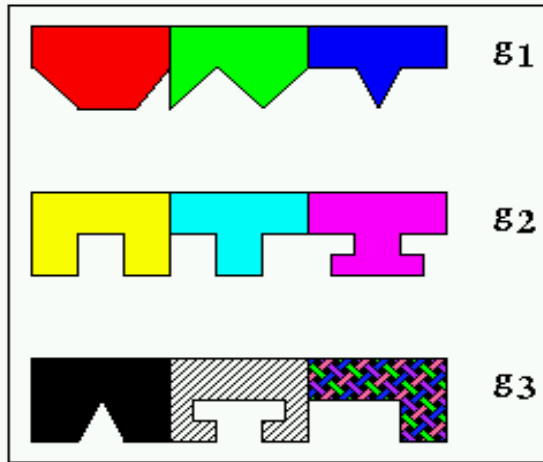
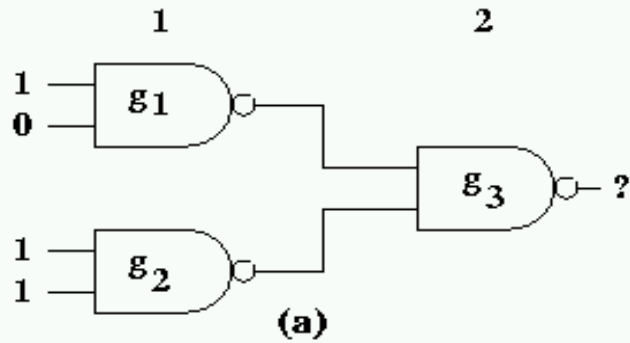
- We have a tube for each circuit level
- Thus, we “pour” the output of gates at one level into the gates at the next level
- Output signals “stick” to next level gates
- We want to destroy gates with both input sections covered, since they have both inputs equal to 1
- Achieve this with *restriction enzymes*



- We have a tube of DNA for each circuit level
- Each tube contains strands representing gates at that level
- We also create an input tube, containing short strands encoding input values of 1
- These stick to gate strands at level 1
- We then add the restriction enzyme to destroy gate strands with both input strands stuck to them
- Sort on length using gel electrophoresis, and retain only those intact strands
- Add pre-prepared primers and restrict again to “snip off” output sections of retained gate strands
- Sort on length again, this time retaining output sections
- Pour these into the tube representing the next level, and repeat until we reach the final level
- If there are intact strands representing the output gate, the circuit has value 1, otherwise it has value 0



Example



(c)

Applications

- Several applications of *in vitro* computing proposed
- We survey some theoretical and experimental advances in the next lecture

Martyn Amos, Gheorge Paun, Grzegorz Rozenberg and Arto Salomaa, Topics in the Theory of DNA Computing, *Theoretical Computer Science* **287**, pp. 3-38, 2002

Sticker model

- Alternative filtering-style model due to Roweis *et al.*
- Operations performed on multisets of strings over the binary alphabet $\{0, 1\}$
- *Memory* strands are n digits in length, and contain k non-overlapping substrings of length m
- Substrands are numbered contiguously, with no gaps
- Each substrand corresponds to a bit, and may be *on* or *off*

Leonard M. Adleman, Paul W. K. Rothmund, Sam Roweis and Erik Winfree, On Applying Molecular Computation To The Data Encryption Standard, Proc. DNA Computing II, 1996.

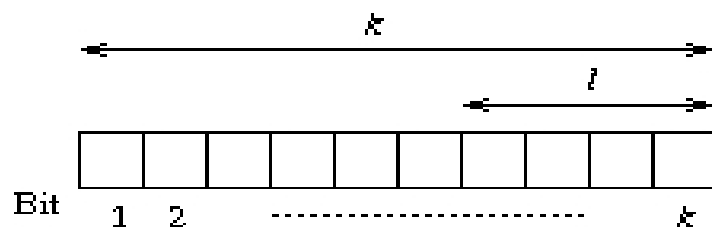
Sticker model operations

- *merge*. Create multiset union of two tubes
- *separate(N,i)*. Given a tube N and an integer i , create two new tubes $+(N,i)$ and $-(N,i)$, where $+(N,i)$ contains all strings in N with bit i set to *on* (and $-(N,i)$ to *off*)
- *set(N,i)*. Produce a new tube from N in which the i th bit of every memory strand is set to *on*
- *clear(N,i)*. Produce a new tube from N in which the i th bit of every memory strand is set to *off*

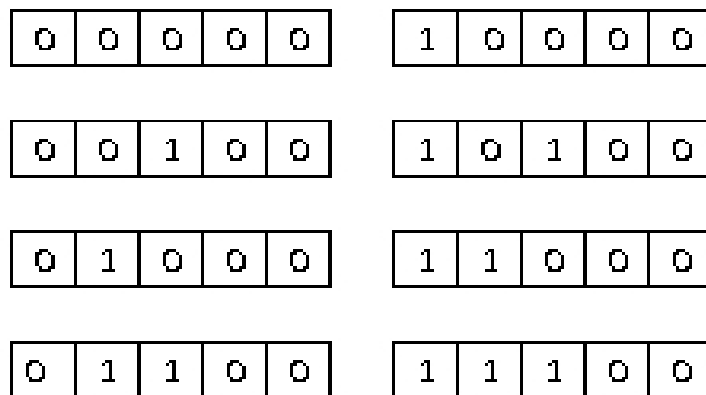
Sticker model computations

- Initial input to a computation consists of a *library* of memory strands
- A (k, l) library, where $1 \leq l \leq k$, consists of memory strands with k bits, the first l of which may be either *on* or *off*, and the last $k-l$ of which are *off*
- In an initial tube the first l bits represent the input to the computation, and the remainder are used for working storage and output

Sticker model strand scheme



(a)



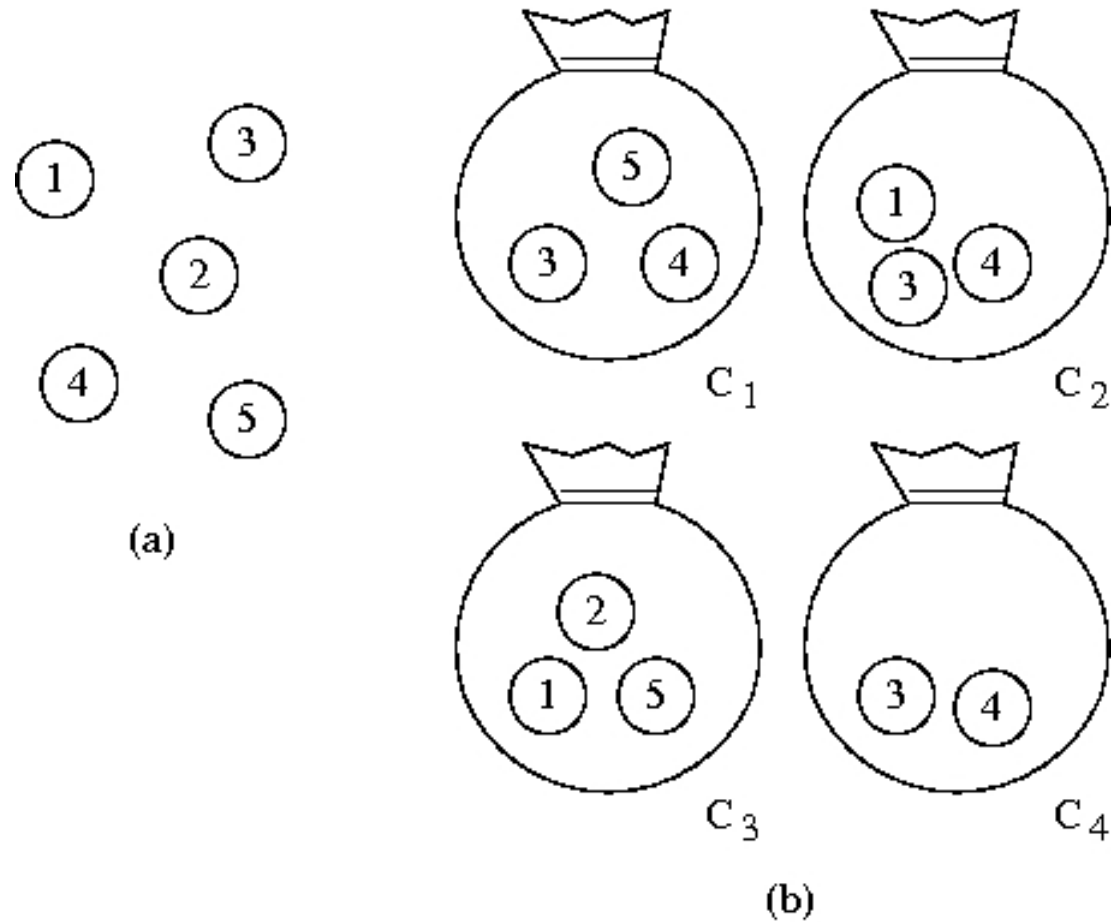
(b)

Complete $(5,2)$ library

Example algorithm

- Sticker solution to the *Minimal Set Cover Problem*
- Given a set of different *objects* and a set of *bags* containing different subsets of the possible set of objects, what is the smallest number of bags a person must hold to ensure she has at least one of each object?

Example problem



Algorithm

- In previous example, $p=5$, $q=4$
- Memory strands have $k=p+q$ bits, and the initial tube N_0 contains a $(p+q, q)$ library
- Each memory strand represents a possible subset of bags from set C , with the first q bits encoding the presence/absence of bags
- Working bits represent the subset of *objects* encompassed by the bags “held”

Algorithm

- For example, a memory strand encoding 010110110 is interpreted as follows:
- The first four bits encode the fact that bags C_2 and C_4 are held;

010110110

- $C_2 \cup C_4 = \{1,3,4\}$, represented by the last 5 bits

010110110

Algorithm

- When initial library created, working bits are all set to off, so we need to set them to appropriate values
- For a given memory strand, take the total subset of objects encoded by all of the bags it “holds” and use *set* to turn on the bits representing each object from that subset



Table 3.1. N_0 after setup

M	C_1	C_2	C_3	C_4	1	2	3	4	5	Subset
1	0	0	0	0	0	0	0	0	0	empty
2	0	0	0	1	0	0	1	1	5	(3,4,5)
3	0	0	1	0	1	1	0	0	1	(1,2,5)
4	0	0	1	1	1	1	1	1	1	(1,2,3,4,5)
5	0	1	0	0	1	0	1	1	0	(1,3,4)
6	0	1	0	1	1	0	1	1	0	(1,3,4)
7	0	1	1	0	1	1	1	1	1	(1,2,3,4,5)
8	0	1	1	1	1	1	1	1	1	(1,2,3,4,5)
9	1	0	0	0	0	0	1	1	1	(3,4,5)
10	1	0	0	1	0	0	1	1	1	(3,4,5)
11	1	0	1	0	1	1	1	1	1	(1,2,3,4,5)
12	1	0	1	1	1	1	1	1	1	(1,2,3,4,5)
13	1	1	0	0	1	0	1	1	1	(1,3,4,5)
14	1	1	0	1	1	0	1	1	1	(1,3,4,5)
15	1	1	1	0	1	1	1	1	1	(1,2,3,4,5)
16	1	1	1	1	1	1	1	1	1	(1,2,3,4,5)

Algorithm

- Now that we have this initial library, we first wish to retain only those that *cover* the full set of objects (that is, subsets that contain one of each object)
- We achieve this by discarding strands that *do not* have each of their working bits set to *on*
- This gives us the strands depicted on the next slide



Table 3.2. N_0 after culling

M	C_1	C_2	C_3	C_4	1	2	3	4	5	Subset
4	0	0	1	1	1	1	1	1	1	(1,2,3,4,5)
7	0	1	1	0	1	1	1	1	1	(1,2,3,4,5)
8	0	1	1	1	1	1	1	1	1	(1,2,3,4,5)
11	1	0	1	0	1	1	1	1	1	(1,2,3,4,5)
12	1	0	1	1	1	1	1	1	1	(1,2,3,4,5)
15	1	1	1	0	1	1	1	1	1	(1,2,3,4,5)
16	1	1	1	1	1	1	1	1	1	(1,2,3,4,5)

Algorithm

- Once we have established a set of coverings, we then need to find one that uses the *smallest* number of bags
- We sort the initial tube N_0 into a number of tubes N_0, N_1, \dots, N_q , where tube N_i contains memory strands encoding coverings using i bags

Sorting procedure

- This may be visualized as a row of tubes, stretching from left to right, with N_0 at the left, and N_q at the right
- We loop, maintaining a counter i from 1 to 4, each time “dragging” right one tube any strands containing bag i
- Imagine it as an inverted form of GE, where “heavier” strands (those containing more bags) go furthest

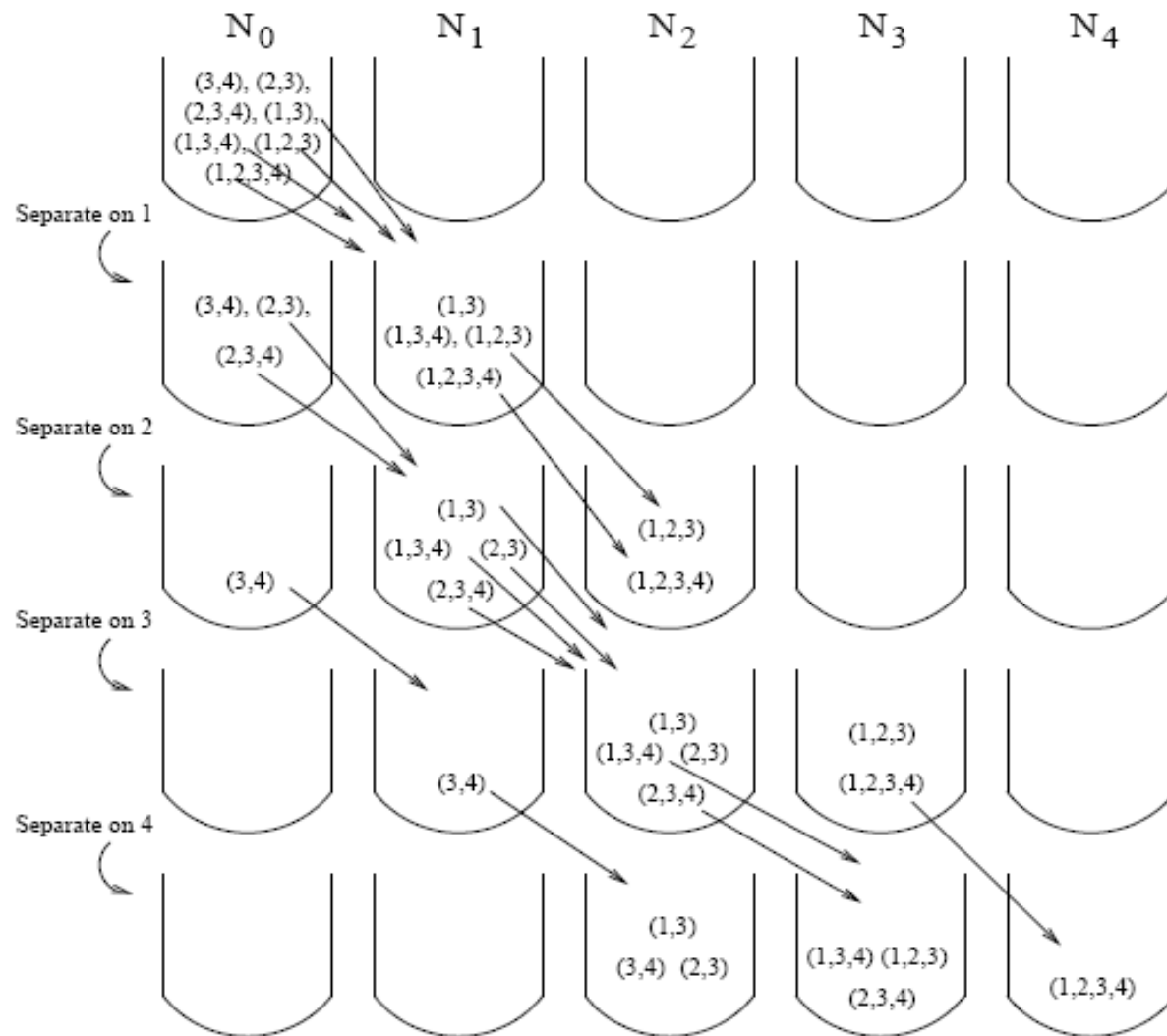


Fig. 3.4. Sorting procedure

Formal algorithm

- (1) Initialize (p,q) library in tube N_0
- (2) **for** $i = 1$ to q **do begin**
- (3) $N_0 \leftarrow \text{separate}_i(+ (N_0, i), - (N_0, i))$
- (4) **for** $j = 1$ to $|C_i|$
- (5) $\text{set}(+ (N_0, i), q + c_i^j)$
- (6) **end for**
- (7) $N_0 \leftarrow \text{merge}(+ (N_0, i), - (N_0, i))$
- (8) **end for**

This section sets the object identifying substrands. Note that c_i^j denotes the j th element of set C_i . We now separate out for further use only those memory complexes where each of the last p substrands is set to on.

- (1) **for** $i = q + 1$ to $q + p$ **do begin**
- (2) $N_0 \leftarrow + (N_0, i)$
- (3) **end for**

Formal algorithm

We now sort the remaining strands according to how many bags they encode.

- (1) **for** $i = 0$ **to** $q - 1$ **do begin**
- (2) **for** $j - 1$ **down to** 0 **do begin**
- (3) *separate*($+(N_j, i + 1), -(N_j, i + 1)$)
- (4) $N_{j+1} \leftarrow \text{merge}(+(N_j, i + 1), N_{j+1})$
- (5) $N_j \leftarrow -(N_j, i + 1)$
- (6) **end for**
- (7) **end for**

Line 3 separates each tube according to the value of i , and line 4 performs the right shift of selected strands. We then search for a final output:

- (1) Read N_1
- (2) **else if empty then** read N_2
- (3) **else if empty then** read N_3
- (4) ...

P systems

- We have already encountered the concept of performing computations by the manipulation of multisets of objects
- This is a well-established form of programming (eg. Petri nets)
- Abstract machines such as the PRAM or TM are sequential in nature
- *Concurrent* models allow multiple processes to execute in parallel

P systems

- The GAMMA (General Abstract Model for Multiset Manipulation) of Banatre and Le Matayer was developed by Berry and Boudol into the *Chemical Abstract Machine*
- Programs viewed almost as *chemical reactions*, with the set being the chemical solution, some reaction *condition* being a property to be satisfied by reacting elements, and some *action* being the resulting product of the reaction
- A computation ends when no further reactions can occur, and a stable state is reached
- Importantly, the CHAM also introduced the notion of a *membrane* construct

Membrane computing

- P systems, a variant of the membrane model, were introduced by Gheorge Paun
- They were inspired by features of biological membranes found in nature
- Membranes act as barriers or filters, separating the cell into distinct regions and controlling the passage of molecules between regions
- *Inspired by, but not intended to model*

Gheorge Paun, *Membrane Computing: An Introduction*. Springer, 2002

P systems

- Membrane structure of a P system is delimited by a *skin* that separates the internals of the system from its outside environment
- Within the skin lies a hierarchical arrangement of membranes that define individual regions
- An *elementary* membrane contains no other membranes, and its region is therefore defined by the space it encloses
- The region defined by a nonelementary membrane is the space between the membrane and the membranes contained directly within it

P systems

- Each region contains a multiset of *objects* and a set of *rules*
- Objects are represented by symbols from a given alphabet
- Rules transform or “evolve” objects, and are of the form *before* \rightarrow *after*, meaning “evolve every instance of *before* into an instance of *after*”
- As we are considering multisets, rules may be applied to multiple objects

P system rules

- Evolution rules are represented by a pair (u, v) of strings over the alphabet V
- v may be either v' or $v'\Delta$, where Δ is a special character not in V
- v' is a string over $\{a_{\text{here}}, a_{\text{out}}, a_{\text{in}_j}\}$, where j is a membrane identifier
- a_{here} means “a copy of a remains in this region”
- a_{out} means “send a copy of a through the membrane and out of this region”
- a_{in_j} means “send a copy of a through the membrane of the region labelled j ” (only possible if the current region contains j)

P system rules

- When the special symbol Δ is encountered, the membrane defining the current region (assuming it is not the skin) is “dissolved”, and the contents placed in the “parent region”
- For simplicity, we omit the “here” subscript, so $a \rightarrow ab$ means “retain a copy of a here and create a copy of b here”
- $a \rightarrow b\Delta$ means “transform every instance of a into an instance of b and dissolve the membrane
- Objects on the LHS of evolution rules are “consumed” (removed) during evaluation

Priority

- We may also impose priorities upon rules
- This is denoted by $>$, and may be read as follows using the example

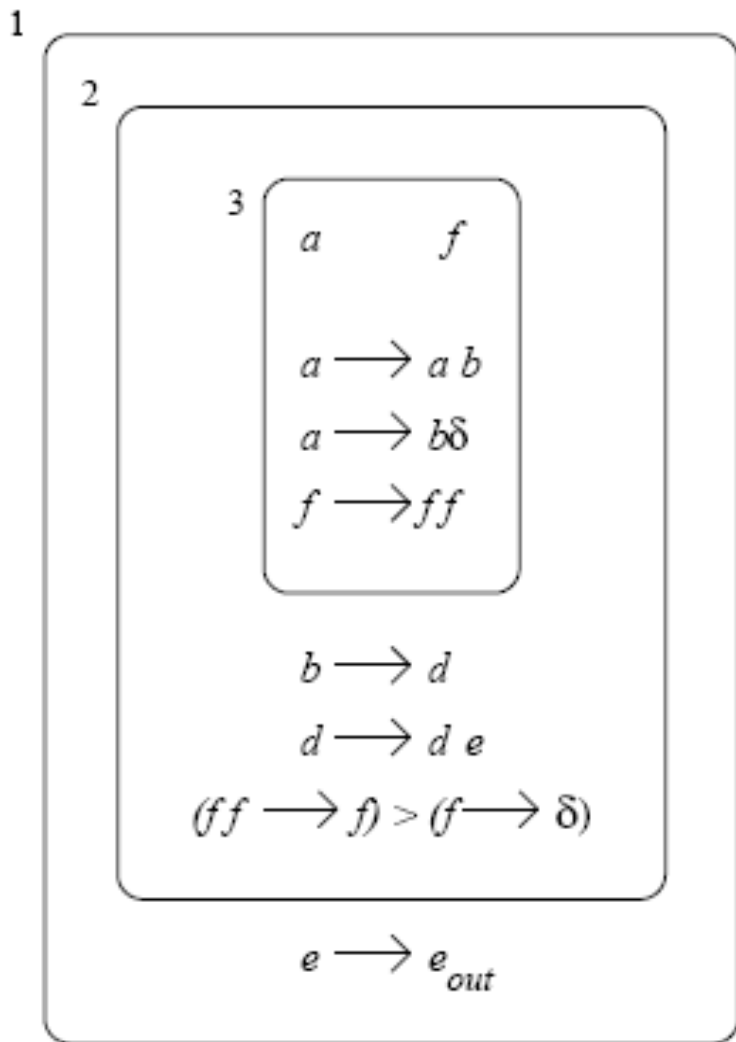
$$(ff \rightarrow f) > (f \rightarrow \Delta)$$

- “Transform ff to f as often as possible (halving the number of occurrences of f) until no instances of ff remain, then transform the one remaining f to Δ , dissolving the membrane”

Synchronization

- We assume the existence of a “clock” that synchronizes the operation of a system
- At each time step, the configuration of the system is transformed by the application of rules in each region to objects, nondeterministically in parallel, until no further assignment is possible
- A computation halts if no rules can be applied in any region
- The result of a halting computation is the number of objects sent out through the skin to the outside environment

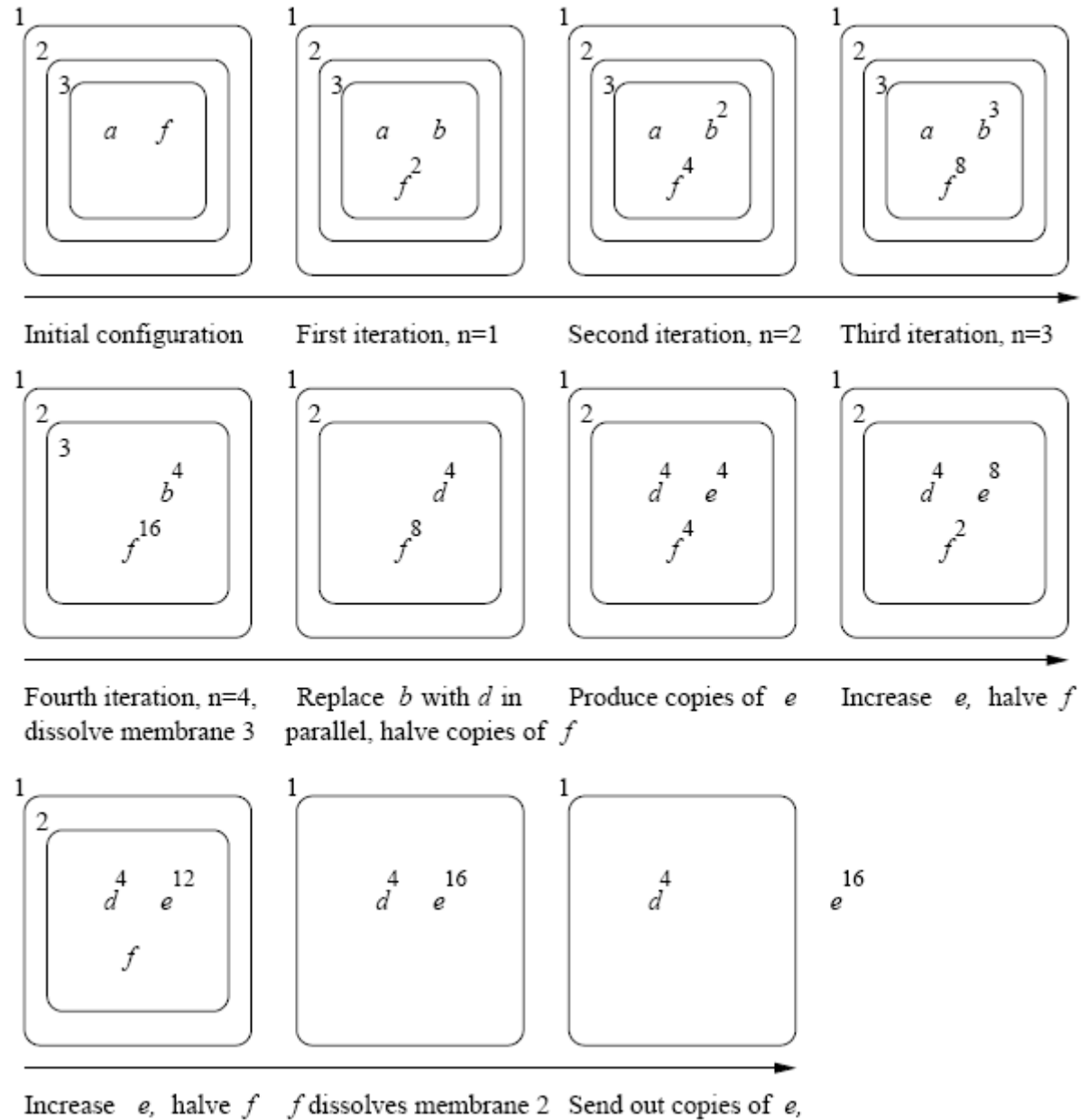
Example



- This P system calculates n^2 for any $n \geq 0$
- Alphabet $V = \{a, b, d, e, f\}$
- Region 3 contains one copy each of a and f , and three evolution rules
- No objects are present in regions 1/2, so no rules can be applied until we reach region 3
- We iterate the rules $a \rightarrow ab$ and $f \rightarrow ff$ n times in parallel, where n is the number we wish to square
- This gives n copies of b and 2^n copies of f
- We then use $a \rightarrow b\delta$, replacing the single a with b and dissolving the membrane
- This leaves $n+1$ copies of b and 2^{n+1} copies of f in region 2
- The rules from region 3 are then “destroyed”, and the rules from region 2 are now used
- Priority dictates that we use $ff \rightarrow f$ as often as possible, so in one time step we halve the number of copies of f and, in parallel, transform b^{n+1} to d^{n+1}
- In the next step, using $d \rightarrow de$, $n+1$ copies of e are produced, and the number of copies of f again halved
- This step is iterated n times, producing $n+1$ copies of e at each step, then the membrane is dissolved
- All objects are deposited in the skin, which sends the copies of e out to the outside environment

Trace for $n=4$

Example from G. Paun,
Computing with
membranes. *J. Comp. Sys.
Sciences* **61**:1, 108-143,
2000



Recent work

- Since the original development of P systems, several variants have emerged (for example, using “charges” rather than membrane labels)
- P systems have been applied to NP-complete problems, and are offering a rich vein of theoretical results and applications
- P.Frisco, D. W. Corne, Dynamics of HIV infection studied with Cellular Automata and conformon-P systems, *BioSystems* **91**:3, 2008, pp. 531-544